

Node Feature Kernels Increase Graph **Convolutional Network Robustness**

Message-Passing Framework

- Graph Convolutional Network (GCN, [3]): $\sigma(AX\Theta)$.
- Input: graph structure \tilde{A} and node features X.
- Procedure: Aggregation step AX and Update step $X\Theta$.

Research Problem

Question 1: What is the influence of the graph structure information and node feature information on each other in the GCN?

Question 2: How will the inference drawn from a GCN be impacted by graph structural noise and is there a way to enhance its robustness to such noise?

Take-away Message

The message-passing step dilutes (or in the extreme case) completely ignores) information present in the node features if the underlying graph structure is noisy (or in the extreme case completely random). Adding a node feature kernel addresses this problem.

- Replace trainable weight Θ with normally distributed matrix, i.e., $\sigma(AXW)$, where $W_{ij} \sim \mathcal{N}(0,1), A \in \mathbb{R}^{n \times n}, X \in \mathbb{R}^{n \times p}$ and $W \in \mathbb{R}^{p \times d}.$
- Insight from this model: we study the spectral behaviour of Gram matrix $G = \frac{1}{d}\sigma(\tilde{A}XW)\sigma(W^{\intercal}X^{\intercal}\tilde{A}^{\intercal})$, specifically the eigenvector of G corresponding to its largest eigenvalue (the *in*formative eigenvector).

Why RandomGCN?

- To enable a Random Matrix Theory (RMT) analysis and its powerful tools in the theoretical study of neural networks.
- Empirically, *Random*GCNs **can** achieve comparable results with the vanilla GCN, i.e., no training is needed for the update weights in high dimensions.



Figure 1: In high dimensions: GCN and *Random*GCN exhibit equivalent performance.

Assumptions

Data Node features follow a Gaussian Mixture Model,

 $x_i = (-1)^a \frac{\mu}{\sqrt{p}} + z_i \quad \text{with} \quad z_i \sim \mathcal{N}(\mathbf{0}, I_p/p).$

Data Graph Structure follows a Stochastic Block Model (SBM),

$$\tilde{A} = \frac{1}{\sqrt{n}} (A - qq^{\mathsf{T}})$$
 where A

RMT Growth Rate Assumptions on the number of nodes, feature dimension, dimension of the random matrix W and edge probabilities.

RMT Regularity Assumptions on the activation function $\sigma(\cdot)$.

Theorem 1 (Informal). The extent to which the labels vector, that we are trying to predict, correlates with the informative eigenvector of the Gram matrix of our RandomGCN depends on the presence of cluster structure in the SBM.

Theorem 2 (Main Corollary). When $\eta = 0$, let $\mathbf{X} = \mathbf{A}\mathbf{X}$ and \bar{y} be the node labels, we have $|\bar{y}^{\intercal}\hat{y}|^2 \xrightarrow[n \to \infty]{} 0$, where \hat{y} is the eigenvector corresponding to the largest eigenvalue of XX^{\intercal} .

- **Observation** If a graph is **sufficiently** perturbed, then the GCN will fail to benefit from the node features **no matter how informa**tive they are.
- Intuitive Explanation In a message-passing framework, node features are aggregated over graph neighbourhoods. When these neighbourhoods are random, we are aggregating random subsets of node features, thus destroying potential information.

Proposed Solution

This can be addressed by using the node feature information to directly inform the structure of the GCNs message passing scheme

$$\epsilon \hat{A} + (1 - \epsilon) \tilde{K}.$$



Figure 2: Adding a node feature kernel helps reconstruct meaningful neighbourhoods.

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 $A_{ij} \sim Ber(q_i q_j C_{ab}).$

We evaluate the robustness of the GCN model on the **node classifica**tion task with two structural perturbation schemes: edge deletion of ratio α and *edge insertion* of ratio β . Consistent with our theoretical analysis, we use a **single-layer** GCN model (with MLP readout). For simplicity we use the **linear kernel** $K_{ij} = x_i^{\mathsf{T}} x_j$ and sparsify the dense kernel with the adjacency matrix $\boldsymbol{K} \circ \hat{\boldsymbol{A}}$.

Stochastic Blockmodels (Community number: 2)

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		SBM(p = 0.25, q = 0.25)		SBM(p = 0.275, q = 0.25)		SBM(p = 0.225, q = 0.25)	
	(lpha,eta)	GCN	GCN-k	GCN	GCN-k	GCN	GCN-k
	$(0.0, \ 0.0)$	50.53 ± 0.49	66.36 ± 0.81	64.42 ± 0.43	62.26 ± 1.04	63.20 ± 0.94	61.03 ± 1.08
Dalation	(0.2,0.0)	51.03 ± 0.56	65.44 ± 1.07	58.63 ± 0.68	71.57 ± 1.42	60.89 ± 0.83	54.91 ± 1.00
Deletion	(0.5, 0.0)	49.29 ± 0.59	64.14 ± 1.01	60.76 ± 1.29	$275, q = 0.25)$ $GCN-k$ 62.26 ± 1.04 71.57 ± 1.42 68.80 ± 2.04 68.20 ± 1.38 66.57 ± 1.73 63.36 ± 1.67 60.16 ± 1.21	58.41 ± 1.11	59.51 ± 2.47
т	(0.0, 0.5)	50.57 ± 0.75	68.57 ± 1.25	60.49 ± 0.40	68.20 ± 1.38	58.82 ± 1.16	63.54 ± 0.97
Insertion	$(0.0, \ 1.0)$	49.19 ± 0.47	59.31 ± 0.58	53.67 ± 1.11	66.57 ± 1.73	54.87 ± 0.53	60.84 ± 0.75
Dolot Incont	(0.5, 0.5)	49.26 ± 0.59	68.84 ± 0.86	50.50 ± 0.37	63.36 ± 1.67	50.94 ± 0.86	63.02 ± 0.91
Delet.+Illsert.	(0.5, 1.0)	49.84 ± 0.69	65.49 ± 1.22	48.34 ± 0.22	$275, q = 0.25)$ $GCN-k$ 62.26 ± 1.04 71.57 ± 1.42 68.80 ± 2.04 68.20 ± 1.38 66.57 ± 1.73 63.36 ± 1.67 60.16 ± 1.21	49.23 ± 0.45	59.64 ± 1.33

* The performance of the GCN degrades on SBMs with cluster structure (homophilic/heterophilic) as a result of *edge-deletion* and *edge-insertion* noise. * Addition of the proposed kernel improves GCNs robustness against graph struc-

tural noise.

Citation/Co-purchase/Co-author graphs

		CoraFull		Photo			
	(lpha,eta)	GCN	GCN-k	GCN	GCN-k	GCN	GCN-k
	$(0.0, \ 0.0)$	57.21 ± 0.84	56.88 ± 0.48	90.94 ± 0.49	90.09 ± 0.65	92.89 ± 0.41	92.63 ± 0.31
Deletion	$(0.2,\ 0.0)$	57.25 ± 0.67	55.56 ± 0.69	91.87 ± 0.40	92.19 ± 0.45	90.58 ± 0.48	90.89 ± 0.48
Deletion	$(0.5,\ 0.0)$	53.90 ± 0.70	54.62 ± 0.87	91.10 ± 0.40	to GCN-k 90.09 ± 0.65 92.19 ± 0.45 87.97 ± 0.54 84.18 ± 1.27 79.58 ± 1.80 74.65 ± 2.36 63.73 ± 5.04	89.75 ± 0.60	91.27 ± 0.67
Incontion	(0.0, 0.5)	48.11 ± 0.89	51.79 ± 0.65	82.79 ± 1.43	84.18 ± 1.27	87.16 ± 0.65	90.81 ± 0.70
msertion	$(0.0, \ 1.0)$	41.76 ± 1.03	51.91 ± 1.00	72.70 ± 6.40	79.58 ± 1.80	80.34 ± 0.80	90.61 ± 0.37
Delet.+Insert.	(0.5, 0.5)	34.70 ± 0.47	46.50 ± 0.61	69.70 ± 3.70	74.65 ± 2.36	73.75 ± 0.98	87.28 ± 0.72
	(0.5, 1.0)	27.50 ± 1.04	43.04 ± 0.77	61.13 ± 2.49	63.73 ± 5.04	66.26 ± 0.95	87.51 ± 0.58
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* *Edge-insertion* noise seems to have a greater impact on real-world graphs.

* Node feature kernel can largely compensate the performance reduction caused

by graph structural noise.

Deeper GCN model (4 layers)

	(lpha,eta)	GCN	GCN-k ($\epsilon = 0.5$)	GCN-k ($\epsilon = 0.2$)	GCN-jk	GCNII	GCN-k-jk
	(0.0, 0.0)	88.44 ± 0.84	89.81 ± 0.52	91.64 ± 0.39	90.19 ± 0.59	92.13 ± 0.39	91.73 ± 0.26
Dolotion	(0.2, 0.0)	89.19 ± 0.57	88.41 ± 0.53	91.68 ± 0.55	91.04 ± 0.65	91.56 ± 0.53	$\mathbf{\overline{91.89}\pm0.77}$
Deletion	(0.5, 0.0)	86.68 ± 0.57	86.17 ± 1.06	91.03 ± 0.03 91.03 ± 0.03 91.03 ± 0.03 1.06 88.91 ± 0.62 88.4 1.19 88.84 ± 0.57 87.3	88.44 ± 0.69	90.01 ± 0.69	91.43 ± 0.60
т ,•	(0.0, 0.5)	70.94 ± 2.59	84.36 ± 1.19	88.84 ± 0.57	87.37 ± 0.66	$\overline{90.36\pm0.58}$	92.66 ± 0.49
Insertion	(0.0, 1.0)	35.84 ± 6.91	81.06 ± 3.94	88.27 ± 0.92	81.70 ± 0.63	$\overline{89.33 \pm 1.02}$	91.42 ± 0.48
Delet.+Insert.	(0.5, 0.5)	45.08 ± 4.82	76.27 ± 1.08	82.23 ± 1.08	73.08 ± 1.07	$\mathbf{\overline{88.66} \pm 0.70}$	87.53 ± 0.85
	(0.5, 1.0)	18.16 ± 3.86	53.12 ± 6.21	80.80 ± 0.99	63.84 ± 0.95	88.77 ± 0.89	$\overline{87.89\pm0.37}$
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* Our proposed kernel performs better or on par with Jumping Knowledge [5] and **GCNII** [1] under all noise schemes. * It can be further **combined with** JK to improve the performance.

We also observed similar GraphSage[2] and GAT[4]).

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behaviour	for	other	GNNs	$(\operatorname{GIN}[6],$
More experi	ment	s are o	n our pa	per.

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